

Understanding Digital Signal Processing Solution

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u[n] = y[n + 1] - 0.4y[n]. Substituting this in the second equation we get after some. y[n + 1] = s[n] - 0.4y[n] - 0.18y[n - 1] + 0.8y[n - 2]. Making use of the first. y[n] + 0.4y[n - 1] + 0.18y[n - 2] - 0.2y[n - 3] = 0.6x[n - 1] + 0.3x[n - 2] + 0.2x[n - 3].

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x (n) = cos (2 p f o n t s + f) + cos (2 p f o n t s) where ts is the time between your x (n) samples, and f is a constant phase shift measured in radians. An example x (n) when f = p / 2 is shown in Figure P1 - 13 where the x (n) sequence, represented by the circular dots, is a single sinusoid whose frequency is fo Hz.

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The book discusses receiving signals that most electrical engineers detect and study. The vast majority of signals could never be detected due to random additive signals, known as noise, that distorts them or completely overshadows them. Such examples include an audio signal of the pilot communicating with the ground over the engine noise or a bioengineer listening for a fetus ' heartbeat ...

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